A characterization of farsightedly stable networks under the componentwise egalitarian allocation rule

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Abstract

We study the stability of social and economic networks when players are farsighted. We adopt Herings, Mauleon and Vannetelbosch’s [Games and Economic Behavior 67, 526-541 (2009)] notions of farsightedly stable set and of myopically stable set. We first provide an algorithm that characterizes the unique pairwise and groupwise farsightedly stable set of networks. We then show that this set only coincides with the unique groupwise myopically stable set of networks. We conclude that, under the componentwise egalitarian allocation rule, (i) if players are allowed to deviate in groups then whether players are farsighted or myopic does not matter; (ii) if players are farsighted then whether players are allowed to deviate in pairs only or in groups does not matter. Finally, we provide some primitive conditions on value functions so that the set of strongly efficient networks belongs to the unique farsightedly stable set.

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1 Introduction

The organization of individual agents into networks and groups or coalitions plays an important role in the determination of the outcome of many social and economic interactions. For instance, networks of personal contacts are important in obtaining information on goods and services, like product information or information about job opportunities. Many commodities are traded through networks of buyers and sellers. A simple way to analyze the networks that one might expect to emerge in the long run is to examine the requirement that individuals do not benefit from altering the structure of the network. An example of such a condition is the pairwise stability notion defined by Jackson and Wolinsky (1996).\(^1\) Their approach is static and myopic. Individuals are not forward-looking in the sense that they do not forecast how others might react to their actions. But, individuals might not add a link that appears valuable to them given the current network, as that might in turn lead to the formation of other links and ultimately lower the payoffs of the original individuals.

Herings, Mauleon and Vannetelbosch (2009) have proposed the notion of pairwise farsightedly stable sets of networks that predicts which networks one might expect to emerge in the long run when players are farsighted.\(^2\) A set of networks \(G\) is pairwise farsightedly stable (i) if all possible farsighted pairwise deviations from any network \(g \in G\) to a network outside \(G\) are deterred by the threat of ending worse off or equally well off, (ii) if there exists a farsighted improving path from any network outside the set leading to some network in the set,\(^3\) and (iii) if there is no proper subset of \(G\) satisfying Conditions (i) and (ii). A non-empty pairwise farsightedly stable set always exists. Herings, Mauleon and Vannetelbosch (2009) have provided a full characterization of unique pairwise farsightedly stable sets of networks.

\(^1\)Jackson (2003, 2005) provides surveys of models of network formation.

\(^2\)Other approaches to farsightedness in network formation are suggested by the work of Xue (1998), Herings, Mauleon, and Vannetelbosch (2004), Mauleon and Vannetelbosch (2004), Page, Wooders and Kamat (2005), Dutta, Ghosal, and Ray (2005), and Page and Wooders (2009).

\(^3\)A farsighted improving path is a sequence of networks that can emerge when players form or sever links based on the improvement the end network offers relative to the current network. Each network in the sequence differs by one link from the previous one. If a link is added, then the two players involved must both prefer the end network to the current network, with at least one of the two strictly preferring the end network. If a link is deleted, then it must be that at least one of the two players involved in the link strictly prefers the end network.
In this paper we provide an algorithm that characterizes the unique pairwise and groupwise farsightedly stable set of networks. We then show that this set only coincides with the unique groupwise myopically stable set of networks. We conclude that, under the componentwise egalitarian allocation rule, (i) if players are allowed to deviate in groups then whether players are farsighted or myopic does not matter; (ii) if players are farsighted then whether players are allowed to deviate in pairs only or in groups does not matter. Finally, we provide some primitive conditions on value functions so that the set of strongly efficient networks belongs to the unique farsightedly stable set.

The paper is organized as follows. In Section 2 we introduce some notations and basic properties and definitions for networks. In Section 3 we define the myopic and farsighted notion stable set of networks. In Section 4 we characterize the farsighted stable set of networks under the componentwise egalitarian allocation rule. In Section 5 we study the relationship between farsighted stability and other concepts of farsighted stability such as the largest consistent set, the von Neumann-Morgenstern farsightedly stable set and the path dominance core. We look at the relationship between farsighted stability and efficiency of networks in Section 6.

2 Networks

Let $N = \{1, \ldots, n\}$ be the finite set of players who are connected in some network relationship. The network relationships are reciprocal and the network is thus modeled as a non-directed graph. Individuals are the nodes in the graph and links indicate bilateral relationships between individuals. Thus, a network $g$ is simply a list of which pairs of individuals are linked to each other. We write $ij \in g$ to indicate that $i$ and $j$ are linked under the network $g$. Let $g^S$ be the set of all subsets of $S \subseteq N$ of size 2. So, $g^N$ is the complete network. The set of all possible networks or graphs on $N$ is denoted by $\mathcal{G}$ and consists of all subsets of $g^N$. The network obtained by adding link $ij$ to an existing network $g$ is denoted $g+ij$ and the network that results from deleting link $ij$ from an existing network $g$ is denoted $g-ij$. For any network $g$, let $N(g) = \{i \mid \exists j \text{ such that } ij \in g\}$ be the set of players who have at least one link in the network $g$. A path in a network $g \in \mathcal{G}$ between $i$ and $j$ is a sequence of

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4Throughout the paper we use the notation $\subseteq$ for weak inclusion and $\subset$ for strict inclusion. Finally, $\#$ will refer to the notion of cardinality.
players \( i_1, \ldots, i_K \) such that \( i_k i_{k+1} \in g \) for each \( k \in \{1, \ldots, K - 1\} \) with \( i_1 = i \) and \( i_K = j \). A non-empty network \( h \subseteq g \) is a component of \( g \), if for all \( i \in N(h) \) and \( j \in N(h) \setminus \{i\} \), there exists a path in \( h \) connecting \( i \) and \( j \), and for any \( i \in N(h) \) and \( j \in N(g) \), \( ij \in g \) implies \( ij \in h \). The set of components of \( g \) is denoted by \( C(g) \). Knowing the components of a network, we can partition the players into groups within which players are connected. Let \( \Pi(g) \) denote the partition of \( N \) induced by the network \( g \).

A value function is a function \( v : \mathcal{G} \rightarrow \mathbb{R} \) that keeps track of how the total societal value varies across different networks. The set of all possible value functions is denoted by \( \mathcal{V} \). An allocation rule is a function \( Y : \mathcal{G} \times \mathcal{V} \rightarrow \mathbb{R}^N \) that keeps track of how the value is allocated among the players forming a network. It satisfies \( \sum_{i \in N} Y_i(g, v) = v(g) \) for all \( v \) and \( g \).

Jackson and Wolinsky (1996) have proposed a number of basic properties of value functions and allocation rules. A value function is component additive if \( v(g) = \sum_{h \in C(g)} v(h) \) for all \( g \in \mathcal{G} \). Component additive value functions are the ones for which the value of a network is the sum of the value of its components. An allocation rule \( Y \) is component balanced if for any component additive \( v \in \mathcal{V} \), \( g \in \mathcal{G} \), and \( h \in C(g) \), we have \( \sum_{i \in N(h)} Y_i(h, v) = v(h) \). Component balancedness only puts conditions on \( Y \) for \( v \)'s that are component additive, so \( Y \) can be arbitrary otherwise. Given a permutation of players \( \pi \) and any \( g \in \mathcal{G} \), let \( g^\pi = \{ \pi(i)\pi(j) \mid ij \in g \} \). Thus, \( g^\pi \) is a network that is identical to \( g \) up to a permutation of the players. A value function is anonymous if for any permutation \( \pi \) and any \( g \in \mathcal{G} \), \( v(g^\pi) = v(g) \). Given a permutation \( \pi \), let \( v^\pi \) be defined by \( v^\pi(g) = v(g^{\pi^{-1}}) \) for each \( g \in \mathcal{G} \). An allocation rule \( Y \) is anonymous if for any \( v \in \mathcal{V} \), \( g \in \mathcal{G} \), and permutation \( \pi \), we have \( Y_{\pi(i)}(g^\pi, v^\pi) = Y_i(g, v) \).

An allocation rule that is component balanced and anonymous is the componentwise egalitarian allocation rule. For a component additive \( v \) and network \( g \), the componentwise egalitarian allocation rule \( Y^{ce} \) is such that for any \( h \in C(g) \) and each \( i \in N(h) \), \( Y_i^{ce}(g, v) = v(h)/\#N(h) \). For a \( v \) that is not component additive, \( Y^{ce}(g, v) = v(g)/n \) for all \( g \); thus, \( Y^{ce} \) splits the value \( v(g) \) equally among all players if \( v \) is not component additive.

In evaluating societal welfare, we may take various perspectives. A network \( g \) is Pareto efficient relative to \( v \) and \( Y \) if there does not exist any \( g' \in \mathcal{G} \) such that \( Y_i(g', v) \geq Y_i(g, v) \) for all \( i \) with at least one strict inequality. A network \( g \in \mathcal{G} \) is
strongly efficient relative to \( v \) if \( v(g) \geq v(g') \) for all \( g' \in G \). This is a strong notion of efficiency as it takes the perspective that value is fully transferable.

Which networks are likely to emerge in the long run? The game-theoretic approach to network formation uses two different notions of a deviation by a coalition. *Pairwise deviations* (Jackson and Wolinsky, 1996) are deviations involving a single link at a time. Moreover, link addition is bilateral (two players that would be involved in the link must agree to adding the link), link deletion is unilateral (at least one player involved in the link must agree to deleting the link), and network changes take place one link at a time. *Groupwise deviations* (Jackson and van den Nouweland, 2005) are deviations involving several links and some group of players at a time. Link addition is bilateral, link deletion is unilateral, and multiple link changes can take place at a time. Whether a pairwise deviation or a groupwise deviation makes more sense will depend on the setting within which network formation takes place. The definitions of stability we consider allows for a deviation by a coalition to be valid only if all members of the coalition are strictly better off. It is customary to require that a coalition deviates only if all members are made better off since changing the status-quo is costly, and players have to be compensated for doing so.\(^5\)

### 3 Definitions of stable sets of networks

#### 3.1 Myopic definitions

We first introduce the notion of pairwise myopically stable sets of networks due to Herings, Mauleon and Vannetelbosch (2009) which is a generalization of Jackson and Wolinsky (1996) pairwise stability notion.\(^6\) Pairwise stable networks do not always exist. A pairwise myopically stable set of networks is a set such that from any network outside this set, there is a myopic improving path leading to some network

\(^5\)But sometimes some players may be indifferent between the network they face and an alternative network, while others are better off at this network structure. Then, it should not be too difficult for the players who are better off to convince the indifferent players to join them to move towards this network structure when very small transfers among the deviating group of players are allowed.

\(^6\)A network \( g \in G \) is pairwise stable with respect \( v \) and \( Y \) if no player benefits from severing one of their links and no two players benefit from adding a link between them. The original definition of Jackson and Wolinsky (1996) allows for a pairwise deviation to be valid if one deviating player is better off and the other one is at least as well off.
in the set, and each deviation outside the set is deterred because the deviating players do not prefer the resulting network. The notion of a myopic improving path was first introduced in Jackson and Watts (2002). A myopic improving path is a sequence of networks that can emerge when players form or sever links based on the improvement the resulting network offers relative to the current network. Each network in the sequence differs by one link from the previous one. If a link is added, then the two players involved must both prefer the resulting network to the current network. If a link is deleted, then it must be that at least one of the two players involved in the link prefers the resulting network.

Formally, a pairwise myopic improving path from a network $g$ to a network $g' \neq g$ is a finite sequence of networks $g_1, \ldots, g_K$ with $g_1 = g$ and $g_K = g'$ such that for any $k \in \{1, \ldots, K - 1\}$ either: (i) $g_{k+1} = g_k - ij$ for some $ij$ such that $Y_i(g_{k+1}, v) > Y_i(g_k, v)$ or $Y_j(g_{k+1}, v) > Y_j(g_k, v)$, or (ii) $g_{k+1} = g_k + ij$ for some $ij$ such that $Y_i(g_{k+1}, v) > Y_i(g_k, v)$ and $Y_j(g_{k+1}, v) > Y_j(g_k, v)$. For a given network $g$, let $m(g)$ be the set of networks that can be reached by a pairwise myopic improving path from $g$.

**Definition 1.** A set of networks $G \subseteq \mathbb{G}$ is pairwise myopically stable with respect to $v$ and $Y$ if

(i) $\forall g \in G$,

   (ia) $\forall ij \notin g$ such that $g + ij \notin G$, $Y_i(g + ij, v) \leq Y_i(g, v)$ or $Y_j(g + ij, v) \leq Y_j(g, v)$,

   (ib) $\forall ij \in g$ such that $g - ij \notin G$, $Y_i(g - ij, v) \leq Y_i(g, v)$ and $Y_j(g - ij, v) \leq Y_j(g, v)$,

(ii) $\forall g' \in \mathbb{G} \setminus G$, $m(g') \cap G \neq \emptyset$,

(iii) $\not\exists G' \subsetneq G$ such that $G'$ satisfies Conditions (ia), (ib), and (ii).

Conditions (ia) and (ib) in Definition 1 capture deterrence of external deviations. In Condition (ia) the addition of a link $ij$ to a network $g \in G$ that leads to a network outside $G$ is deterred because the two players involved do not prefer the resulting network to network $g$. Condition (ib) is a similar requirement, but then for the case where a link is severed. Condition (ii) requires external stability. External stability asks for the existence of a pairwise myopic improving path from any network outside
$G$ leading to some network in $G$. Condition (ii) implies that if a set of networks is pairwise myopically stable, it is non-empty. Notice that the set $G$ (trivially) satisfies Conditions (ia), (ib), and (ii) in Definition 1. This motivates Condition (iii), the minimal condition.

Jackson and Watts (2002) have defined the notion of a closed cycle. A set of networks $C$ is a cycle if for any $g \in C$ and $g' \in C \setminus \{g\}$, there exists a pairwise myopic improving path connecting $g$ to $g'$. A cycle $C$ is a maximal cycle if it is not a proper subset of a cycle. A cycle $C$ is a closed cycle if no network in $C$ lies on a pairwise myopic improving path leading to a network that is not in $C$. A closed cycle is necessarily a maximal cycle. Herings, Mauleon and Vannetelbosch (2009) have shown that the set of networks consisting of all networks that belong to a closed cycle is the unique pairwise myopically stable set.

The notion of pairwise myopically stable set only considers deviations by at most a pair of players at a time. It might be that some group of players could all be made better off by some complicated reorganization of their links, which is not accounted for under pairwise myopic stability. A network $g' \in G$ is obtainable from $g \in G$ via deviations by group $S \subseteq N$ if (i) $ij \in g'$ and $ij \notin g$ implies $\{i, j\} \subseteq S$, and (ii) $ij \in g$ and $ij \notin g'$ implies $\{i, j\} \cap S \neq \emptyset$.

A groupwise myopic improving path from a network $g$ to a network $g' \neq g$ is a finite sequence of networks $g_1, \ldots, g_K$ with $g_1 = g$ and $g_K = g'$ such that for any $k \in \{1, \ldots, K - 1\}$ : $g_{k+1}$ is obtainable from $g_k$ via deviations by $S_k \subseteq N$ and $Y_i(g_{k+1}, v) > Y_i(g_k, v)$ for all $i \in S_k$. For a given network $g$, let $M(g)$ be the set of networks that can be reached by a groupwise myopic improving path from $g$.

**Definition 2.** A set of networks $G \subseteq G$ is groupwise myopically stable with respect to $v$ and $Y$ if

(i) $\forall g \in G, S \subseteq N, g' \notin G$ that is obtainable from $g$ via deviations by $S$, there exists $i \in S$ such that $Y_i(g', v) \leq Y_i(g, v)$,

(ii) $\forall g' \in G \setminus G, M(g') \cap G \neq \emptyset$,

(iii) $\nexists G' \subset G$ such that $G'$ satisfies Conditions (ia), (ib), and (ii).

Replacing the notion of pairwise improving path by the notion of groupwise improving path in the definition of a closed cycle, we have that the set of networks
consisting of all networks that belong to a closed cycle is the unique groupwise my-
opically stable set. The notion of groupwise myopically stable set is a generalization
of Dutta and Mutuswami (1997) strong stability notion. In Figure 1 we have de-
picted an example where the unique pairwise myopically stable set is \(g_0, g_7\) while
the unique groupwise myopically stable set is \(g_7\). Indeed, there is no network
such that there is a pairwise myopic improving path from any other network leading
to it. More precisely, \(m(g_0) = \emptyset\), \(m(g_1) = \{g_0, g_4, g_6, g_7\}\), \(m(g_2) = \{g_0, g_4, g_5, g_7\}\),
\(m(g_3) = \{g_0, g_5, g_6, g_7\}\), \(m(g_4) = \{g_7\}\), \(m(g_5) = \{g_7\}\), \(m(g_6) = \{g_7\}\), and \(m(g_7) = \emptyset\).

Hence, a set formed by the empty network \(g_0\) and the complete network \(g_7\) is
a pairwise myopically stable set. However, the groupwise myopically stable set
consists only of the complete network. Indeed, we have \(M(g_0) = \{g_4, g_5, g_6, g_7\}\),
\(M(g_1) = \{g_0, g_4, g_5, g_6, g_7\}\), \(M(g_2) = \{g_0, g_4, g_5, g_6, g_7\}\), \(M(g_3) = \{g_0, g_4, g_5, g_6, g_7\}\),
\(M(g_4) = \{g_7\}\), \(M(g_5) = \{g_7\}\), \(M(g_6) = \{g_7\}\), and \(M(g_7) = \emptyset\).

\(\begin{array}{ccc}
Pl.1 & 0 & 0 \\
\bullet & \bullet & Pl.3 \\
\end{array} \)

\(\begin{array}{cccc}
\begin{array}{c}
0 \\
Pl.2 \\
\end{array} & \begin{array}{c}
g_0 \\
0 \\
\end{array} & \begin{array}{c}
g_1 \\
0 \\
\end{array} & \begin{array}{c}
g_2 \\
-1 \\
\end{array} & \begin{array}{c}
g_3 \\
-1 \\
\end{array} \\
\end{array} \)

\(\begin{array}{cccc}
\begin{array}{c}
g_4 \\
1 \\
\end{array} & \begin{array}{c}
g_5 \\
1 \\
\end{array} & \begin{array}{c}
g_6 \\
1 \\
\end{array} & \begin{array}{c}
g_7 \\
2 \\
\end{array} \\
\end{array} \)

Figure 1: An example without cycles.

In Figure 2 we have depicted Jackson and Wolinsky co-author model with three
players. It is easy verified that the complete network \(g_7\) is the unique pairwise stable
network. Moreover, it is easy to demonstrate that the pairwise myopically stable

\(\text{A set } g \text{ is strongly stable stable with respect } v \text{ and } Y \text{ if } \forall S \subseteq N, \ g' \text{ that is obtainable from } g \text{ via deviations by } S, \text{ there exists } i \in S \text{ such that } Y_i(g', v) \leq Y_i(g, v) \text{. } \) Jackson and van den
Nouweland (2005) have introduced a slightly stronger definition where a deviation is valid if some
members are better off and others are at least as well off. For many value functions and allocation
rules these definitions coincide.
set is \( \{g_7\} \). However, there is no strongly stable network. The groupwise myopically stable set is \( \{g_1, g_2, g_3, g_4, g_5, g_6, g_7\} \) and consists only of cycles. Indeed, we have \( M(g_0) = \{g_1, g_2, g_3, g_4, g_5, g_6, g_7\} \), \( M(g_1) = \{g_1, g_2, g_3, g_4, g_5, g_6, g_7\} \), \( M(g_2) = \{g_1, g_2, g_3, g_4, g_5, g_6, g_7\} \), \( M(g_3) = \{g_1, g_2, g_3, g_4, g_5, g_6, g_7\} \), \( M(g_4) = \{g_1, g_2, g_3, g_4, g_5, g_6, g_7\} \), \( M(g_5) = \{g_1, g_2, g_3, g_4, g_5, g_6, g_7\} \), \( M(g_6) = \{g_1, g_2, g_3, g_4, g_5, g_6, g_7\} \), and \( M(g_7) = \{g_1, g_2, g_3, g_4, g_5, g_6, g_7\} \).

\[ \begin{array}{cccccc}
0 & 0 & 0 & 3 & 3 & 3 \\
\bullet & \bullet & \bullet & \bullet & \bullet & \bullet \\
0 & 0 & 3 & 3 & 0 & 0 \\
\text{Pl.1} & \text{Pl.3} & \text{Pl.2} & g_0 & g_1 & g_2 \\
\end{array} \]

\[ \begin{array}{cccccc}
4 & 2 & 2 & 4 & 2 & 2 \\
4 & 2 & 2 & 2.5 & 2.5 & 2.5 \\
g_4 & g_5 & g_6 & g_7 & g_7 & g_7 \\
\end{array} \]

Figure 2: The co-author model with three players.

### 3.2 Farsighted definitions

A **pairwise farsighted improving path** is a sequence of networks that can emerge when players form or sever links based on the improvement the end network offers relative to the current network. Each network in the sequence differs by one link from the previous one. If a link is added, then the two players involved must both strictly prefer the end network to the current network. If a link is deleted, then it must be that at least one of the two players involved in the link prefers the end network. Formally, a pairwise farsighted improving path from a network \( g \) to a network \( g' \neq g \) is a finite sequence of networks \( g_1, \ldots, g_K \) with \( g_1 = g \) and \( g_K = g' \) such that for any \( k \in \{1, \ldots, K - 1\} \) either: (i) \( g_{k+1} = g_k - ij \) for some \( ij \) such that \( Y_i(g_K, v) > Y_i(g_k, v) \) or \( Y_j(g_K, v) > Y_j(g_k, v) \), or (ii) \( g_{k+1} = g_k + ij \) for some \( ij \) such that \( Y_i(g_K, v) > Y_i(g_k, v) \) and \( Y_j(g_K, v) > Y_j(g_k, v) \). For a given network \( g \), let \( f(g) \)
be the set of networks that can be reached by a pairwise farsighted improving path from $g$.

We now give the definition of a pairwise farsightedly stable set due to Herings, Mauleon and Vannetelbosch (2009).

**Definition 3.** A set of networks $G \subseteq \mathbb{G}$ is a pairwise farsightedly stable set with respect $v$ and $Y$ if

(i) $\forall g \in G$,

(ia) $\forall ij \notin g$ such that $g + ij \notin G$, $\exists g' \in f(g + ij) \cap G$ such that $Y_i(g', v) \leq Y_i(g, v)$ or $Y_j(g', v) \leq Y_j(g, v)$,

(ib) $\forall ij \in g$ such that $g - ij \notin G$, $\exists g', g'' \in f(g - ij) \cap G$ such that $Y_i(g', v) \leq Y_i(g, v)$ and $Y_j(g'', v) \leq Y_j(g, v)$,

(ii) $\forall g' \in \mathbb{G} \setminus G$, $f(g') \cap G \neq \emptyset$.

(iii) $\not\exists G' \subsetneq G$ such that $G'$ satisfies Conditions (ia), (ib), and (ii).

Condition (i) in Definition 3 requires the deterrence of external deviations. Condition (ia) captures that adding a link $ij$ to a network $g \in G$ that leads to a network outside of $G$, is deterred by the threat of ending in $g'$. Here $g'$ is such that there is a pairwise farsighted improving path from $g + ij$ to $g'$. Moreover, $g'$ belongs to $G$, which makes $g'$ a credible threat. Condition (ib) is a similar requirement, but then for the case where a link is severed. Condition (ii) in Definition 3 requires external stability and implies that the networks within the set are robust to perturbations. From any network outside of $G$ there is a farsighted improving path leading to some network in $G$. Condition (ii) implies that if a set of networks is pairwise farsightedly stable, it is non-empty. Notice that the set $\mathbb{G}$ (trivially) satisfies Conditions (ia), (ib), and (ii) in Definition 3. This motivates the requirement of a minimality condition, namely Condition (iii). Herings, Mauleon and Vannetelbosch (2009) have shown that a pairwise farsightedly stable set of networks always exists.$^8$

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A network $g$ strictly Pareto dominates all other networks if $g$ is such that for all $g' \in \mathbb{G} \setminus \{g\}$ it holds that, for all $i$, $Y_i(g, v) > Y_i(g', v)$. Although the network that strictly Pareto dominates all others is pairwise stable, there might be many more pairwise stable networks. Herings, Mauleon and Vannetelbosch (2009) have shown that, if there is a network $g$ that strictly Pareto dominates all other networks, then $\{g\}$ is the unique pairwise farsightedly stable set. Thus, pairwise farsighted stability singles out the Pareto dominating network as the unique pairwise farsightedly stable set.

A groupwise farsighted improving path from a network $g$ to a network $g' \neq g$ is a finite sequence of networks $g_1, \ldots, g_K$ with $g_1 = g$ and $g_K = g'$ such that for any $k \in \{1, \ldots, K - 1\}$: $g_{k+1}$ is obtainable from $g_k$ via deviations by $S_k \subseteq N$ and $Y_i(g_{k+1}, v) > Y_i(g_K, v)$ for all $i \in S_k$. For a given network $g$, let $F(g)$ be the set of networks that can be reached by a groupwise farsighted improving path from $g$.

**Definition 4.** A set of networks $G \subseteq \mathbb{G}$ is groupwise farsightedly stable with respect $v$ and $Y$ if

(i) $\forall g \in G$, $S \subseteq N$, $g' \notin G$ that is obtainable from $g$ via deviations by $S$, there exists $g'' \in F(g') \cap G$ such that $Y_i(g'', v) \leq Y_i(g, v)$ for some $i \in S$,

(ii) $\forall g' \in \mathbb{G} \setminus G$, $F(g') \cap G \neq \emptyset$,

(iii) $\nexists G' \subseteq G$ such that $G'$ satisfies Conditions (ia), (ib), and (ii).

Let us reconsider the co-author model with three players depicted in Figure 2. No singleton set is pairwise farsightedly stable. Indeed, there is no network such that there is a farsighted improving path from any other network leading to it. More precisely, $f(g_0) = \{g_1, g_2, g_3, g_4, g_5, g_6\}$, $f(g_1) = \{g_4, g_5\}$, $f(g_2) = \{g_4, g_6\}$, $f(g_3) = \{g_5, g_6\}$, $f(g_4) = \{g_7\}$, $f(g_5) = \{g_7\}$, $f(g_6) = \{g_7\}$, and $f(g_7) = \emptyset$. However, a set formed by the complete and two star networks is a pairwise farsightedly stable set of networks. The pairwise farsightedly stable sets are $\{g_4, g_5, g_7\}$, $\{g_4, g_6, g_7\}$, $\{g_5, g_6, g_7\}$, and $\{g_1, g_2, g_3, g_7\}$ in the co-author model with three players. Suppose that we allow now for groupwise deviations. Then, we have $F(g_0) = \{g_1, g_2, g_3, g_4, g_5, g_6\}$, $F(g_1) = \{g_4, g_5\}$, $F(g_2) = \{g_4, g_6\}$, $F(g_3) = \{g_5, g_6\}$, $F(g_4) = \{g_4, g_7\}$, $F(g_5) = \{g_2, g_7\}$, $F(g_6) = \{g_1, g_7\}$, and $F(g_7) = \{g_1, g_2, g_3\}$. Hence, $\{g_1, g_2, g_3\}$ becomes a groupwise farsightedly stable set. But, this is not the unique groupwise farsightedly stable set. The others are $\{g_2, g_3, g_5, g_6\}$, $\{g_2, g_3, g_4, g_6\}$,
\{g_1, g_3, g_4, g_5\}, \{g_1, g_3, g_5, g_6\}, \{g_1, g_2, g_4, g_5\}, \{g_1, g_2, g_4, g_6\}, \{g_4, g_5, g_7\}, \{g_4, g_6, g_7\},
\{g_5, g_6, g_7\}.

4 Stable sets of networks under the componentwise egalitarian allocation rule

We now investigate whether the pairwise or groupwise farsighted stability coincide or not with the pairwise or groupwise myopically stability under the componentwise egalitarian allocation. Let

\[ g(v, S) = \left\{ g \subseteq g^S \left| \frac{v(g)}{\#N(g)} \geq \frac{v(g')}{\#N(g')} \forall g' \subseteq g^S \right. \right\} \]

be the set of networks with the highest per capita value out of those that can be formed by players in \( S \subseteq N \). Given a component additive value function \( v \), find a network \( g^v \) through the following algorithm due to Banerjee (1999). Pick some \( h_1 \in g(v, N) \). Next, pick some \( h_2 \in g(v, N \setminus N(h_1)) \). At stage \( k \) pick some \( h_k \in g(v, N \setminus \bigcup_{i \leq k-1} N(h_i)) \). Since \( N \) is finite this process stops after a finite number \( K \) of stages. The union of the components picked in this way defines a network \( g^v \). We denote by \( G^v \) the set of all networks that can be found through this algorithm. More than one network may be picked up through this algorithm since players may be permuted or even be indifferent between components of different sizes.

Lemma 1. Consider any anonymous and component additive value function \( v \). For all \( g \in G^v \) we have \( f(g) = \emptyset \) and \( F(g) = \emptyset \) under the componentwise egalitarian allocation rule \( Y^{ce} \).

Proof. Take any \( g \in G^v \) where \( g = \bigcup_{k=1}^{K} h_k \) with \( h_k \in g(v, N \setminus \bigcup_{i \leq k-1} N(h_i)) \). Players belonging to \( N(h_1) \) in \( g \) who are looking forward will never engage in a move since they can never be strictly better off than in \( g \) given the componentwise egalitarian allocation rule \( Y^{ce} \). Players belonging to \( N(h_2) \) in \( g \) who are forward looking will never engage in a move since the only possibility to obtain a strictly higher payoff is to end up in \( h_1 \) (if \( h_1 \) gives a strictly higher payoff than \( h_2 \)) but players belonging to \( N(h_1) \) will never engage a move. So, players belonging to \( N(h_2) \) can never end up strictly better off than in \( g \) given the componentwise egalitarian allocation rule \( Y^{ce} \). Players belonging to \( N(h_k) \) in \( g \) who are forward looking will never engage in a move since the only possibility to obtain a strictly higher payoff is to end up in
Corollary 1. Consider any anonymous and component additive value function $v$. For all $g \in G^v$ we have $m(g) = \emptyset$ and $M(g) = \emptyset$ under the componentwise egalitarian allocation rule $Y^{ce}$. 

Lemma 2. Consider any anonymous and component additive value function $v$. For all $g' \notin G^v$ there exists $g \in G^v$ such that $g \in f(g')$ under the componentwise egalitarian allocation rule $Y^{ce}$. 

Proof. We show in a constructive way that for all $g' \notin G^v$ there exists $g \in G^v$ such that $g \in f(g')$ under the componentwise egalitarian allocation rule $Y^{ce}$. Take any $g' \notin G^v$.

Step 1: If there exists some $h_1 \in g(v, N)$ such that $h_1 \in C(g')$ then go to Step 2 with $g_1 = g'$. Otherwise, pick some $h_3 \in g(v, N)$. In $g'$ all players are strictly worse off than the players belonging to $N(h_3)$ under the componentwise egalitarian allocation rule $Y^{ce}$. From $g'$, let the players who belong to $N(h_1)$ and who are looking forward to $g \in G^v$ such that $h_1 \in C(g)$ first deleting successively all their links and then building successively the links in $h_1$ leading to $g_1 = g' - \{ij \mid i \in N(h_1) \text{ and } ij \notin h_1\} + \{ij \mid i \in N(h_1), ij \in h_1 \text{ and } ij \notin g'\}$. Along the sequence from $g'$ to $g_1$ all players who are moving always prefer the end network $g$ to the current network. Once $g_1$ and $h_1$ are formed, we move to Step 2.

Step 2: If there exists some $h_2 \in g(v, N \setminus N(h_1))$ such that $h_2 \in C(g_1)$ then go to Step 3 with $g_2 = g_1$. Otherwise, pick some $h_2 \in g(v, N \setminus N(h_1))$. In $g_1$ all the remaining players who are belonging to $N \setminus N(h_1)$ are strictly worse off than the players belonging to $N(h_2)$ under the componentwise egalitarian allocation rule $Y^{ce}$. From $g_1$ let the players who belong to $N(h_2)$ and who are looking forward to $g \in G^v$ such that $h_1 \in C(g)$ and $h_2 \in C(g)$ first deleting successively all their links and then building successively the links in $h_2$ leading to $g_2 = g_1 - \{ij \mid i \in N(h_2) \text{ and } ij \notin h_2\} + \{ij \mid i \in N(h_2), ij \in h_2 \text{ and } ij \notin g_1\}$. Along the sequence from $g_1$ to $g_2$ all players who are moving always prefer the...
end network $g$ to the current network. Once $g_2$ and $h_2$ are formed, we move to Step 3.

**Step 3:** If there exists some $h_3 \in g(v, N \setminus \{N(h_1) \cup N(h_2)\})$ such that $h_3 \in C(g_2)$ then go to Step 4 with $g_3 = g_2$. Otherwise, pick some $h_3 \in g(v, N \setminus \{N(h_1) \cup N(h_2)\})$. In $g_2$ all the remaining players who are belonging to $N \setminus \{N(h_1) \cup N(h_2)\}$ are strictly worse off than the players belonging to $N(h_3)$ under the componentwise egalitarian allocation rule $Y^{ce}$. From $g_2$ let the players who belong to $N(h_3)$ and who are looking forward to $g \in G^v$ such that $h_1 \in C(g)$, $h_2 \in C(g)$ and $h_3 \in C(g)$ first deleting successively all their links and then building successively the links in $h_3$ leading to $g_3 = g_2 - \{ij \mid i \in N(h_3) \text{ and } ij \notin h_3\} + \{ij \mid i \in N(h_3), ij \in h_3 \text{ and } ij \notin g_2\}$. Along the sequence from $g_2$ to $g_3$ all players who are moving always prefer the end network $g$ to the current network. Once $g_3$ and $h_3$ are formed, we move to Step 4.

**Step $k$:** If there exists some $h_k \in g(v, N \setminus \{N(h_1) \cup \ldots \cup N(k - 1)\})$ such that $h_k \in C(g_{k-1})$ then go to Step $k + 1$ with $g_k = g_{k-1}$. Otherwise, pick some $h_k \in g(v, N \setminus \{N(h_1) \cup \ldots \cup N(k - 1)\})$. In $g_{k-1}$ all the remaining players who are belonging to $N \setminus \{N(h_1) \cup \ldots \cup N(k - 1)\}$ are strictly worse off than the players belonging to $N(h_k)$ under the componentwise egalitarian allocation rule $Y^{ce}$. From $g_{k-1}$ let the players who belong to $N(h_k)$ and who are looking forward to $g \in G^v$ such that $h_1 \in C(g)$, $h_2 \in C(g)$, $\ldots$ $h_k \in C(g)$ first deleting successively all their links and then building successively the links in $h_k$ leading to $g_k = g_{k-1} - \{ij \mid i \in N(h_k) \text{ and } ij \notin h_k\} + \{ij \mid i \in N(h_k), ij \in h_k \text{ and } ij \notin g_{k-1}\}$. Along the sequence from $g_{k-1}$ to $g_k$ all players who are moving always prefer the end network $g$ to the current network. Once $g_k$ and $h_k$ are formed, we move to Step $k + 1$; and so on until we reach the network $g = \bigcup_{k=1}^{K} h_k$ with $h_k \in g(v, N \setminus \cup_{i \leq k-1} N(h_i))$. Thus, we have build a pairwise farsightedly improving path from $g'$ to $g$; $g \in f(g')$. Since $f(g') \subseteq F(g')$, we also have that for all $g' \notin G^v$ there exists $g \in G^v$ such that $g \in F(g')$ under the componentwise egalitarian allocation rule $Y^{ce}$. 

The next proposition tells us that once players are farsighted it does not matter whether groupwise or only pairwise deviations are feasible. Both pairwise farsighted stability and groupwise farsighted stability single out the same unique set.
Proposition 1. Consider any anonymous and component additive value function \( v \). The set \( G^v \) is both the unique pairwise farsightedly stable set and the unique groupwise farsightedly stable set under the componentwise egalitarian allocation rule \( Y^{ce} \).

Proof. Consider any anonymous and component additive value function \( v \). From Lemma 1 we know that \( f(g) = \emptyset \) and \( F(g) = \emptyset \) for all \( g \in G^v \) under the componentwise egalitarian allocation rule \( Y^{ce} \). From Lemma 2 we have that for all \( g' \notin G^v \) there exists \( g \in G^v \) such that \( g \in f(g') \) under the componentwise egalitarian allocation rule \( Y^{ce} \). Using Theorem 5 in Herings, Mauleon and Vannetelbosch (2009) which says that \( G \) is the unique pairwise farsightedly stable set if and only if \( G = f(g) = \emptyset \) and for every \( g' \notin G \), \( f(g') \cap G \neq \emptyset \), we have that \( G^v \) is the unique pairwise farsightedly stable set. In case of groupwise deviations, Theorem 5 says that \( G \) is the unique groupwise farsightedly stable set if and only if \( G = f(g) = \emptyset \) and for every \( g' \notin G \), \( f(g') \cap G \neq \emptyset \). Thus, we have that \( G^v \) is also the unique groupwise farsightedly stable set.

Lemma 3. Consider any anonymous and component additive value function \( v \). For all \( g' \notin G^v \) there exists \( g \in G^v \) such that \( g \in M(g') \) under the componentwise egalitarian allocation rule \( Y^{ce} \).

Proof. We show in a constructive way that for all \( g' \notin G^v \) there exists \( g \in G^v \) such that \( g \in M(g') \) under the componentwise egalitarian allocation rule \( Y^{ce} \). Take any \( g' \notin G^v \).

Step 1: If there exists some \( h_1 \in g(v, N) \) such that \( h_1 \in C(g') \) then go to Step 2 with \( g_1 = g' \). Otherwise, pick some \( h_1 \in g(v, N) \). In \( g' \) all players are strictly worse off than the players belonging to \( N(h_1) \) under the componentwise egalitarian allocation rule \( Y^{ce} \). Then, we have that all members of \( S_1 = \{i \in N(h_1) \mid ij \in h_1 \text{ and } ij \notin g'\} \cup \{i \in N(h_1) \mid ij \notin h_1 \text{ and } ij \in g'\} \) have incentives to deviate from \( g' \) to \( g_1 = g' - \{ij \mid i \in N(h_1) \text{ and } ij \notin h_1\} + \{ij \mid i \in N(h_1), ij \in h_1 \text{ and } ij \notin g'\} \). Indeed, \( g_1 \) is obtainable from \( g' \) via deviations by \( S_1 \subseteq N \) and \( Y_i(g_1, v) > Y_i(g', v) \) for all \( i \in S_1 \). In words, players who belong to \( N(h_1) \) delete their links in \( g' \) with players not in \( N(h_1) \) and build the missing links of \( h_1 \). Once \( g_1 \) and \( h_1 \) are formed, we move to Step 2.
Step 2: If there exists some \( h_2 \in g(v, N \setminus N(h_1)) \) such that \( h_2 \in C(g_1) \) then go to Step 3 with \( g_2 = g_1 \). Otherwise, pick some \( h_2 \in g(v, N \setminus N(h_1)) \). In \( g_1 \) all the remaining players who are belonging to \( N \setminus N(h_1) \) are strictly worse off than the players belonging to \( N(h_2) \) under the componentwise egalitarian allocation rule \( Y^{ce} \). Then, we have that all members of \( S_2 = \{ i \in N(h_2) \mid ij \in h_2 \text{ and } ij \notin g_1 \} \cup \{ i \in N(h_2) \mid ij \notin h_2 \text{ and } ij \notin g_1 \} \) have incentives to deviate from \( g_1 \) to \( g_2 = g_1 - \{ ij \mid \exists i \in N(h_2) \text{ and } ij \notin h_2 \} + \{ ij \mid i \in N(h_2), ij \notin h_2 \text{ and } ij \notin g_1 \} \). Indeed, \( g_2 \) is obtainable from \( g_1 \) via deviations by \( S_2 \subseteq N \) and \( Y_i(g_2, v) > Y_i(g_1, v) \) for all \( i \in S_2 \). Once \( g_2 \) and \( h_2 \) are formed, we move to Step 3.

Step 3: If there exists some \( h_3 \in g(v, N \setminus \{N(h_1) \cup N(h_2)\}) \) such that \( h_3 \in C(g_2) \) then go to Step 4 with \( g_3 = g_2 \). Otherwise, pick some \( h_3 \in g(v, N \setminus \{N(h_1) \cup N(h_2)\}) \). In \( g_2 \) all the remaining players who are belonging to \( N \setminus \{N(h_1) \cup N(h_2)\} \) are strictly worse off than the players belonging to \( N(h_3) \) under the componentwise egalitarian allocation rule \( Y^{ce} \). Then, we have that all members of \( S_3 = \{ i \in N(h_3) \mid ij \in h_3 \text{ and } ij \notin g_2 \} \cup \{ i \in N(h_3) \mid ij \notin h_3 \text{ and } ij \notin g_2 \} \) have incentives to deviate from \( g_2 \) to \( g_3 = g_2 - \{ ij \mid i \in N(h_3) \text{ and } ij \notin g_3 \} + \{ ij \mid i \in N(h_3), ij \notin h_3 \text{ and } ij \notin g_2 \} \). Indeed, \( g_3 \) is obtainable from \( g_2 \) via deviations by \( S_3 \subseteq N \) and \( Y_i(g_3, v) > Y_i(g_2, v) \) for all \( i \in S_3 \). Once \( g_3 \) and \( h_3 \) are formed, we move to Step 4.

Step \( k \): If there exists some \( h_k \in g(v, N \setminus \{N(h_1) \cup \ldots \cup N(k-1)\}) \) such that \( h_k \in C(g_{k-1}) \) then go to Step \( k + 1 \) with \( g_k = g_{k-1} \). Otherwise, pick some \( h_k \in g(v, N \setminus \{N(h_1) \cup \ldots \cup N(k-1)\}) \). In \( g_{k-1} \) all the remaining players who are belonging to \( N \setminus \{N(h_1) \cup \ldots \cup N(k-1)\} \) are strictly worse off than the players belonging to \( N(h_k) \) under the componentwise egalitarian allocation rule \( Y^{ce} \). Then, we have that all members of \( S_k = \{ i \in N(h_k) \mid ij \in h_k \text{ and } ij \notin g_{k-1} \} \cup \{ i \in N(h_k) \mid ij \notin h_k \text{ and } ij \notin g_{k-1} \} \) have incentives to deviate from \( g_{k-1} \) to \( g_k = g_{k-1} - \{ ij \mid i \in N(h_k) \text{ and } ij \notin h_k \} + \{ ij \mid i \in N(h_k), ij \notin h_k \text{ and } ij \notin g_{k-1} \} \). Indeed, \( g_k \) is obtainable from \( g_{k-1} \) via deviations by \( S_k \subseteq N \) and \( Y_i(g_k, v) > Y_i(g_{k-1}, v) \) for all \( i \in S_k \). Once \( g_k \) and \( h_k \) are formed, we move to Step \( k + 1 \); and so on until we reach the network \( g = \bigcup_{k=1}^{K} h_k \) with \( h_k \in g(v, N \setminus \cup_{i \leq k-1} N(h_i)) \). Thus, we have build a groupwise myopically improving path from \( g' \) to \( g; g \in M(g') \). \( \square \)
The next proposition tells us that once players are myopic it matters whether
groupwise or only pairwise deviations are feasible. Groupwise myopic stability
singles out the same unique set as pairwise and groupwise farsighted stability do. How-
ever, the pairwise myopically stable set may include networks that do not belong to
$G^v$.

**Proposition 2.** Consider any anonymous and component additive value function $v$.
The set $G^v$ is the unique groupwise myopically stable set under the componentwise
egalitarian allocation rule $Y^{ce}$.

**Proof.** Since the set of networks consisting of all networks that belong to a closed
cycle is the unique groupwise myopically stable set, we have to show that the set
of all networks that belong to a closed cycle is $G^v$. From Lemma 3 we know that
for all $g' \not\in G^v$ there exists $g \in G^v$ such that $g \in M(g')$ under the componentwise
egalitarian allocation rule $Y^{ce}$. It follows that all closed cycles belong to $G^v$. Since
$F(g) = \emptyset$ for all $g \in G^v$ we have that $M(g) = \emptyset$ for all $g \in G^v$. So, each $g \in M(g)$
is a closed cycle and $G^v$ is the unique groupwise myopically stable set.

Notice that all networks belonging to $G^v$ are pairwise stable networks in a strict
sense. So, pairwise farsighted stability refines the notion of pairwise stability under
$Y^{ce}$ when deviations are valid only if all deviating players are strictly better off.

## 5 Other notions of farsighted stability

In this section we study the relationship between alternative notions of farsighted
stability and pairwise farsighted stable sets. The largest consistent is a concept that
has been defined in Chwe (1994) for general social environments. By considering a
network as a social environment, we obtain the definition of the largest consistent
set.

**The largest consistent set**

**Definition 5.** $G$ is a consistent set if $\forall g \in G$, $S \subseteq N$, $g' \in G$ that is obtainable
from $g$ via deviations by $S$, there exists $g'' \in F(g') \cap G$ such that $Y_i(g'', v) \leq Y_i(g, v)$
for some $i \in S$. The largest consistent set is the consistent set that contains any
consistent set.
Proposition 3. Consider any anonymous and component additive value function \( v \). The set \( G^v \) is the largest consistent set under the componentwise egalitarian allocation rule \( Y^{ce} \).

Proof. First, we show in a constructive way that any \( g' \notin G^v \) cannot belong to a consistent because there always exists a deviation which is not deterred. Take any \( g' \notin G^v \).

Suppose \( \exists h_1 \in g(v, N) \) such that \( h_1 \in C(g') \). Then, in \( g' \) all players are strictly worse off than the players belonging to \( N(h_1) \) under the componentwise egalitarian allocation rule \( Y^{ce} \). We have that all members of \( S_1 = \{ i \in N(h_1) \mid ij \in h_1 \text{ and } ij \notin g' \} \cup \{ i \in N(h_1) \mid ij \notin h_1 \text{ and } ij \in g' \} \) have incentives to deviate from \( g' \) to \( g'' = g' - \{ ij \mid i \in N(h_1) \text{ and } ij \notin h_1 \} + \{ ij \mid i \in N(h_1) \text{ and } ij \in h_1 \text{ and } ij \notin g' \} \).

Indeed, \( g'' \) is obtainable from \( g' \) via deviations by \( S_1 \subseteq N \) and \( Y_i(g'', v) > Y_i(g', v) \) for all \( i \in S_1 \). In words, players who belong to \( N(h_1) \) delete their links in \( g' \) with players not in \( N(h_1) \) and build the missing links of \( h_1 \). In addition, for any \( g^* \neq g'' \), \( g^* \in \mathbb{G} \), we have that \( Y_i(g'', v) \geq Y_i(g^*, v) \) for all \( i \in S_1 \), \( S_1 \subseteq N(h_1) \). So, for any \( g'' \in F(g'') \) we have \( Y_i(g', v) < Y_i(g'', v) = Y_i(g''', v) \) for all \( i \in S_1 \). Thus, \( g' \) cannot belong to a consistent set.

Suppose that \( \exists h_1 \in g(v, N) \) such that \( h_1 \in C(g') \) but \( \exists h_2 \in g(v, N \setminus N(h_1)) \) such that \( h_2 \in C(g') \). Then, in \( g' \) all players who are belonging to \( N \setminus N(h_1) \) are strictly worse off than the players belonging to \( N(h_2) \) under the componentwise egalitarian allocation rule \( Y^{ce} \). Then, we have that all members of \( S_2 = \{ i \in N(h_2) \mid ij \in h_2 \) and \( ij \notin g' \} \cup \{ i \in N(h_2) \mid ij \notin h_2 \text{ and } ij \in g' \} \) have incentives to deviate from \( g' \) to \( g'' = g' - \{ ij \mid i \in N(h_2) \text{ and } ij \notin h_2 \} + \{ ij \mid i \in N(h_2) \text{ and } ij \in h_2 \text{ and } ij \notin g' \} \).

Indeed, \( g'' \) is obtainable from \( g' \) via deviations by \( S_2 \subseteq N \) and \( Y_i(g'', v) > Y_i(g', v) \) for all \( i \in S_2 \). In addition, for any \( g^* \neq g'' \), \( g^* \in \mathbb{G} \), we have that \( Y_i(g'', v) \geq Y_i(g^*, v) \) for all \( i \in S_2 \), \( S_2 \subseteq N(h_2) \). So, for any \( g'' \in F(g'') \) we have \( Y_i(g', v) < Y_i(g'', v) = Y_i(g''', v) \) for all \( i \in S_2 \). Thus, \( g' \) cannot belong to a consistent set.

Suppose that \( \exists h_1, h_2, h_3, \ldots, h_{k-1} \) with \( h_l \in g(v, N \setminus \{ N(h_1) \cup \ldots \cup N(l-1) \}) \), \( l = 1, \ldots, k-1 \), such that \( h_l \in C(g') \) but \( \exists h_k \in g(v, N \setminus \{ N(h_1) \cup \ldots \cup N(k-1) \}) \) such that \( h_k \in C(g') \). Then, in \( g' \) all players who are belonging to \( N \setminus \{ N(h_1) \cup \ldots \cup N(k-1) \} \) are strictly worse off than the players belonging to \( N(h_k) \) under the componentwise egalitarian allocation rule \( Y^{ce} \). Then, we have that all members of \( S_k = \{ i \in N(h_k) \mid ij \in h_k \text{ and } ij \notin g' \} \cup \{ i \in N(h_k) \mid ij \notin h_k \text{ and } ij \in g' \} \) have incentives to deviate from \( g' \) to \( g'' = g' - \{ ij \mid i \in N(h_k) \text{ and } ij \notin h_k \} + \{ ij \mid i \in N(h_k) \), \( 17 \)
\( ij \in h_k \) and \( ij \notin g' \). Indeed, \( g'' \) is obtainable from \( g' \) via deviations by \( S_k \subseteq N \) and \( Y_i(g'', v) > Y_i(g', v) \) for all \( i \in S_k \). In addition, for any \( g' \neq g'', g^* \in G \), we have that \( Y_i(g'', v) \geq Y_i(g', v) \) for all \( i \in S_k, S_k \subseteq N(h_k) \). So, for any \( g'' \in F(g'') \) we have \( Y_i(g', v) < Y_i(g'', v) = Y_i(g''', v) \) for all \( i \in S_k \). Thus, \( g' \) cannot belong to a consistent set. And so forth.

Second, we have from Lemma 1 that \( F(g) = \emptyset \forall g \in G^v \). Hence, each \( \{g\} \) with \( g \in G^v \) is a consistent set. Thus, \( G^v \) is the largest consistent set under the componentwise egalitarian allocation rule \( Y^{ce} \).

**von Neumann-Morgenstern farsighted stability**

The von Neumann-Morgenstern stable set (von Neumann and Morgenstern, 1953) imposes internal and external stability. Incorporating the notion of farsighted improving paths into the original definition of the von Neumann-Morgenstern stable set, we obtain the von Neumann-Morgenstern farsightedly stable set. von Neumann-Morgenstern farsightedly stable sets do not always exist.

**Definition 6.** The set \( G \) is a von Neumann-Morgenstern pairwise farsightedly stable set if (i) \( \forall g \in G, f(g) \cap G = \emptyset \) and (ii) \( \forall g' \in G \setminus G, f(g') \cap G \neq \emptyset \).

**Definition 7.** The set \( G \) is a von Neumann-Morgenstern groupwise farsightedly stable set if (i) \( \forall g \in G, F(g) \cap G = \emptyset \) and (ii) \( \forall g' \in G \setminus G, F(g') \cap G \neq \emptyset \).

**Proposition 4.** Consider any anonymous and component additive value function \( v \). The set \( G^v \) is both the unique von Neumann-Morgenstern pairwise farsightedly stable set and the unique von Neumann-Morgenstern groupwise farsightedly stable set under the componentwise egalitarian allocation rule \( Y^{ce} \).

**Proof.** From Lemma 1 we have \( f(g) = \emptyset \) and \( F(g) = \emptyset \forall g \in G^v \) and from Lemma 2 we have for all \( g' \notin G^v \) there exists \( g \in G^v \) such that \( g \in f(g') \). Thus, \( G^v \) is both the unique von Neumann-Morgenstern pairwise or groupwise farsightedly stable set under the componentwise egalitarian allocation rule \( Y^{ce} \).

**Path dominance core**

The concept of path dominance core is due to Page and Wooders (2009). We give two versions of their concept, one based on pairwise deviations, another based on groupwise deviations. A network \( g' \in G \) pairwise path dominates network \( g \in G \), if \( g' = g \) or if there exists a finite sequence of networks \( \{g_k\}_{k=0}^K \) in \( G \) with \( g_K = g' \) and \( g_0 = g \) such that for \( k = 1, 2, ..., K \), \( g_k \in f(g_{k-1}) \). Similarly, a network \( g' \in G \)
groupwise path dominates network \( g \in \mathcal{G} \), if \( g' = g \) or if there exists a finite sequence of networks \( \{g_k\}_{k=0}^K \) in \( \mathcal{G} \) with \( g_K = g' \) and \( g_0 = g \) such that for \( k = 1, 2, ..., K \), \( g_k \in F(g_{k-1}) \).9

**Definition 8.** A network \( g \in \mathcal{G} \) is contained in the pairwise path dominance core \( \mathcal{C}_p \subseteq \mathcal{G} \) with respect \( v \) and \( Y \) if and only if there does not exist a network \( g' \in \mathcal{G}, \ g' \neq g \), such that \( g' \in f(g) \). A network \( g \in \mathcal{G} \) is contained in the groupwise path dominance core \( \mathcal{C}_p \subseteq \mathcal{G} \) with respect \( v \) and \( Y \) if and only if there does not exist a network \( g' \in \mathcal{G}, \ g' \neq g \), such that \( g' \in F(g) \).

**Proposition 5.** Consider any anonymous and component additive value function \( v \). The set \( \mathcal{G}^v \) is both the pairwise and groupwise path dominance core under the componentwise egalitarian allocation rule \( Y^{ce} \).

**Proof.** First, a network \( g \in \mathcal{G} \) is contained in the pairwise path dominance core \( \mathcal{C}_p \subseteq \mathcal{G} \) with respect \( v \) and \( Y \) if and only if \( f(g) = \emptyset \) and a network \( g \in \mathcal{G} \) is contained in the groupwise path dominance core \( \mathcal{C}_p \subseteq \mathcal{G} \) with respect \( v \) and \( Y \) if and only if \( F(g) = \emptyset \). We show that \( \mathcal{G}^v \) is both the pairwise and groupwise path dominance core. It is immediate from Lemma 1 that all \( g \in \mathcal{G}^v \) belong to the (pairwise or groupwise) path dominance core. From Lemma 2 we have that for all \( g' \notin \mathcal{G}^v \) there exists \( g \in \mathcal{G}^v \) such that \( g \in f(g') \) under the componentwise egalitarian allocation rule \( Y^{ce} \). Hence, for all \( g' \notin \mathcal{G}^v \) we have \( F(g') \neq \emptyset \). Thus, all \( g' \notin \mathcal{G}^v \) do not belong to the (pairwise or groupwise) path dominance core.

### 6 Efficiency and stability

Grandjean, Mauleon and Vannetelbosch (2009) have shown that the set of strongly efficient networks \( E(v) \) is the unique (weak) pairwise farsightedly stable set under \( Y^{ce} \) if and only if the value function \( v \) is top convex. Weak pairwise farsighted stability is the counterpart of the version of pairwise farsighted stability we use here when deviations are valid if both deviating players are at least as well off and one of them is strictly better off. A value function \( v \) is **top convex** if some strongly efficient network also maximizes the per capita value among players. Let

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9In general, the pairwise (groupwise) path dominance core is contained in each pairwise (groupwise) farsightedly stable set of networks. However, a path dominance core may fail to exist while a pairwise (groupwise) farsightedly stable set always exists.
$\rho(v, S) = \max_{g \leq g \leq v} v(g)/\#S$. The value function $v$ is \textit{top convex} if $\rho(v, N) \geq \rho(v, S)$ for all $S \subseteq N$.

Top convexity implies that all components of a strongly efficient network must lead to the same per-capita value (if some component led to a lower per capita value than the average, then another component would have to lead to a higher per capita value than the average which would contradict top convexity). It follows that under the componentwise egalitarian allocation rule any $g \in E(v)$ (strictly) Pareto dominates all $g' \notin E(v)$ Then, it is immediate that $g \in f(g')$ for all $g' \in G \setminus E(v)$ and that $f(g) = \emptyset$. Using Theorem 5 in Herings, Mauleon and Vannetelbosch (2009) which says that $G$ is the unique pairwise farsightedly stable set if and only if $G = \{g \in G \mid f(g) = \emptyset\}$ and for every $g' \in G \setminus G, f(g') \cap G \neq \emptyset$, we have that $E(v)$ is the unique pairwise farsightedly stable set. Thus, if $v$ is top convex then the set of strongly efficient networks $E(v)$ is the unique pairwise farsightedly stable set under $Y^{ce}$. The following example reveals that under the notion of (strict) pairwise farsightedly stable set, top convexity is not necessary to sustain the set of strongly efficient networks as the unique pairwise farsightedly stable set.

\textbf{Example 1.} Let $\#N = 5$. Consider a component additive value function where the value to a component is 30 if it is a line of 3 players, is 20 if it is a line of 2 players, and is 0 otherwise. The set of strongly efficient networks $E(v)$ is the set of networks composed of two lines, one of 3 players and another of 2 players. Suppose that the value is allocated to the agents according to the componentwise egalitarian allocation rule $Y^{ce}$. The value function of this game is not top convex. As such, $E(v)$ is not the unique weak pairwise farsightedly stable set of networks. The (strict) pairwise farsightedly stable set of networks coincide with $E(v)$.

We define a weaker condition, low convexity and show that if a value function is top convex, then it is low convex but that the converse does not hold. We show that under the componentwise egalitarian allocation rule $Y^{ce}$, the set of strongly efficient networks $E(v)$ is contained in the unique strict pairwise farsightedly stable set of networks $G^v$ if and only if $v$ is low convex.

Take an efficient network $g$. A value function is low convex if for each network $g' \neq g$ and each component $h'$ of $g'$, the per capita value of the component $h'$ is not bigger than the one generated by some component $h$ that belongs to the set of components of $g$ for which at least one player belongs to $h$ and to $h'$. 

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Definition 1. Let \( g \in E(v) \). The value function \( v \) is low convex if for all \( g' \neq g \) and for all \( h' \in C(g') \) such that \( N(h') \cap N(g) \neq \emptyset \), \( v(h')/\#N(h') \leq v(h)/\#N(h) \) for some \( h \in C(g) \) such that \( N(h) \cap N(h') \neq \emptyset \).

Proposition 6. Consider an anonymous and component additive value function \( v \).

(i) If \( v \) is top convex, then \( v \) is low convex, but (ii) the reverse is not true.

Proof. Let \( v \) be an anonymous and component additive value function. (i) Let \( v \) also satisfy top convexity. Let \( g \in E(v) \). Top convexity implies that all components of a strongly efficient network must lead to the same per-capita value (if some component led to a lower per capita value than the average, then another component would have to lead to a higher per capita value than the average which would contradict top convexity). Thus for all \( h, h' \in C(g) \), \( v(h)/\#N(h) = v(h')/\#N(h') \). From this, it follows that each component of a strongly efficient network generates at least the same per capita value than any component of another network as otherwise top convexity would violated. For all \( h \in C(g) \), for all \( h' \in C(g') \) where \( g' \neq g \), we have that \( v(h)/\#N(h) \geq v(h')/\#N(h') \). This implies that the value function \( v \) is low convex.

(ii) Consider again Example 1. This value function satisfies low convexity, but not top convexity.

Proposition 7. Consider any anonymous and component additive value function \( v \).

Under the componentwise egalitarian allocation rule \( Y^{ce} \), the set of strongly efficient networks \( E(v) \) is contained in the unique pairwise farsightedly stable set of networks \( G^v \) if and only if \( v \) is low convex.

Proof. Consider any anonymous and component additive value function \( v \). Notice that \( G^v \) is the unique pairwise farsightedly stable set of networks under the componentwise egalitarian allocation rule \( Y^{ce} \). (\( \Leftarrow \)) From Theorem 5 in Herings, Mauleon and Vannetebosch (2009), we know that \( G^v = \{ g \in \mathbb{G} \mid f(g) = \emptyset \} \). We thus only have to show that \( f(g) = \emptyset \) if \( g \in E(v) \) when \( v \) is low convex. Without loss of generality, let \( g = \bigcup_{i=1}^k h_i \) be such that \( v(h_l)/\#N(h_l) \geq v(h_m)/\#N(h_m) \) if \( l < m \). Note that under the componentwise egalitarian allocation rule, the payoff of player \( i \) in component \( h'' \) of network \( g'' \in \mathbb{G} \) is given by \( Y_i^{ce}(g'', v) = v(h'')/\#N(h'') \). Players from \( N(h_1) \) do not take part in any pairwise farsighted improving path emanating from the network \( g \) since in every other network \( g' \), low convexity implies
that $Y_i^{ce}(g', v) \leq Y_i^{ce}(g, v)$ for all $i \in N(h_1)$. The rest of the proof proceeds by induction. Suppose players from $N(h_1)$ to $N(h_l)$ do not participate in a pairwise farsighted improving path emanating from the network $g$. We have to show that players from $N(h_{l+1})$ do not take part in a pairwise farsighted improving path from $g$. Let $S = N(h_1) \cup \ldots \cup N(h_l)$. Every network $g' = g|_{S} \cup \tilde{g}$ where $\tilde{g} \subseteq g^{N\backslash S}$ is such that $Y_i^{ce}(g', v) \leq Y_i^{ce}(g, v)$ for all $i \in N(h_{l+1})$ by low convexity. Thus, if agents from $S$ do not take part in a pairwise farsighted improving path, then agents from $N(h_{l+1})$ do not take part in such move either. We have shown so far that any pairwise farsighted improving path emanating from $g$ does not involve players that are connected under $g$. If every player is connected under $g$, $f(g) = \emptyset$. If one player is not connected under $g$, he does not have the power to change the network without the consent of another player, but we have just established that each other player does not take part in a move from $g$, thus $f(g) = \emptyset$. Finally, if more than one agent is not connected under $g$, then by strong efficiency of $g$ and by component additivity, $v(\tilde{g}) \leq v(g^0)$ for any $\tilde{g} \subseteq g^{N\backslash N(g)}$, implying that there are no pairwise farsighted improving path involving players from $N \backslash N(g)$ only. Thus, $f(g) = \emptyset$.

$(\Rightarrow)$ Suppose by contradiction that $E(v) \subseteq G^v$, and that low convexity is not satisfied. Then, there exists a pair of networks $g \in E(v)$ and $g' \neq g$ such that $v(h')/#N(h') > v(h)/#N(h)$ for some $h' \in C(g')$ such that $N(h') \cap N(g) \neq \emptyset$, for all $h \in C(g)$ such that $N(h) \cap N(h') \neq \emptyset$. Without loss of generality, let $g = \cup_{i=1}^{j} h_i$ be such that $v(h_i)/#N(h_i) \geq v(h_m)/#N(h_m)$ if $l < m$. Since $g \in G^v$, $h_1 \in \text{argmax}_{g \subseteq g^v} v(\tilde{g})/#N(\tilde{g})$. Thus, $h'$ is such that $N(h') \cap N(h_1) = \emptyset$. The rest of the proof proceeds by induction. Suppose that $h'$ is such that $N(h') \cap N(h_j) = \emptyset$ for all $h_j \leq h_l$. Then, we have to show that $h'$ is such that $N(h') \cap N(h_{l+1}) = \emptyset$. Let $S = N(h_1) \cup N(h_2) \cup \ldots \cup N(h_l)$. We have that $h_{l+1} \in \text{argmax}_{g \subseteq g^v} v(\tilde{g})/#N(\tilde{g})$ since $g \in G^v$. Then, $v(h_{l+1})/#N(h_{l+1}) \geq v(h')/#N(h')$ since $N(h') \cap S = \emptyset$. This establishes that $N(h') \cap N(h_{l+1}) = \emptyset$. Thus, $N(h') \cap N(g) = \emptyset$, a contradiction.  

7 Conclusion

We have studied the stability of social and economic networks when players are farsighted. We have adopted Herings, Mauleon and Vannetelbosch’s [Games and Economic Behavior 67, 526-541 (2009)] notions of farsightedly stable set and of
myopically stable set. We have first provided an algorithm that characterizes the unique pairwise and groupwise farsightedly stable set of networks. We have then shown that this set only coincides with the unique groupwise myopically stable set of networks. We have concluded that, under the componentwise egalitarian allocation rule, (i) if players are allowed to deviate in groups then whether players are farsighted or myopic does not matter; (ii) if players are farsighted then whether players are allowed to deviate in pairs only or in groups does not matter. Finally, we have provided some primitive conditions on value functions so that the set of strongly efficient networks belongs to the unique farsightedly stable set.

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